R&D UDR GPS CAN Sensor

Overview

This stand-alone CAN based GPS/GNSS Untethered Dead Reckoning (UDR) sensor outputs latitude, longitude, altitude, Course Over Ground and speed at up to 20Hz.

The strength of UDR is even with complete GPS/GNSS signal loss the unit can provide continuous positioning by using inbuilt inertial sensors to estimate its location, speed etc. it requires no external input to do this. The effect from multipath is also reduced due to having inertial sensors.

The configurable CAN bus speed and address along with the supplied DBC file allows easy integration into almost any vehicle with a CAN bus.

The choice of 6 pin IP67 connector or 300mm pig tail, wide ranging input voltage and the small size and mass of the unit allows easy interface into most vehicles.

30

22x40x45

grams

mm

	1		
Position accuracy	CEP (50%)	2.5	m
UDR Position Error	Typical Position Error after 60 seconds of no signal	<10	%
Acquisition	Cold starts	26	S
	Aided starts	3	S
	Reacquisition	1	S
Supported GNSS Constellations	GPS/QZSS L1 C/A GLONASS L10F BeiDou B11 Galileo E1B/C		
Number of concurrent GNSS	3		
Position/COG/Speed Update Rate		20	Hz
UDR Inertial Sensors	accelerometers	+-4	g
	gyros	250	deg/s

Environment	Operating temperature	-20 to +80	C
	Dust and Water Ingress	IP65	
Mechanical Shock (Max Values)	Duration < 200µs	10000	g
	Duration < 1ms	2000	g
	Free Fall Distance	1.8	m

Cable Variant (standard is 300mm in length)			
AWG	26		
Wire Spec	Raychem 55		
Cable Jacket	TE Flame Retardant -75 to +150°C		
OD	3.1mm +-0.1mm		
Connector Variant			
On Unit	B06B-JWPF-SK-R		
Mating [7]	06R-JWPF-VSLE-D		
Crimp	SWPR-001T-P025		
Pin Outs			
Wire Colour	Pin No.	Function	
Brown	1	Not Used	
Red	2	Supply Voltage	
Black	3	Ground	
Green	4	CAN High	
White	5	CAN Low	
Yellow	6	Factory Reset [8]	

[1] The default settings are 1000kbps and start address 768 (0x310), the unit has no CAN termination

[2] The unit uses 5 CAN addresses which are in consecutive order from the address that the unit is set to.

[3] This connector is not supplied with the unit.

[4] By default this mode is switched off, if it is enabled connect this pin to 2.5v to supply voltage to wake unit.

[5] To reset the unit to factory settings pull this from 2.5v to supply voltage on unit power up.

CAN [1]	Baud Rates	1000, 500, 250	kbps
	Address Range[2]	1 (0x01) to 2042 (0x7FA). Default = 0x310	decimal (Hex)

Height x Width x Length

Power	Voltage Range	9-16	V
	Current (Sleep)	110 (10mA)	mA @ 12V
Input Pins	Voltage Range	2-28	V

Mass

Dimensions

